Yafei Ou

Education

2021 – present **Ph.D., Control Systems**, *University of Alberta*, Edmonton, Canada. Supervisor: Dr. Mahdi Tavakoli. GPA: 4.0.

2017 – 2021 Bachelor of Engineering, Mechanical Design, Manufacturing and Automation, University of Electronic Science and Technology of China, Chengdu, China. GPA: 3.98.

Publications

Journal Articles

- 2024 Yafei Ou and Mahdi Tavakoli. Autonomous soft-tissue needle steering using reinforcement learning guided by human input. *Journal of Medical Robotics Research (JMRR)*, page 2440010. World Scientific Publishing Company, 2024.
- 2024 **Yafei Ou**, Abed Soleymani, Xingyu Li, and Mahdi Tavakoli. Autonomous blood suction for robot-assisted surgery: A sim-to-real reinforcement learning approach. *IEEE Robotics and Automation Letters (RA-L)*, volume 9, pages 7246–7253. IEEE, 2024.
- 2024 Abed Soleymani, Mahdi Tavakoli, Aghazadeh Farzad, **Yafei Ou**, Rouhani Hossein, Bin Zheng, and Xingyu Li. Hands collaboration evaluation for surgical skills assessment: An information theoretical approach. *IEEE Transactions on Medical Robotics and Bionics* (*T-MRB*). IEEE, 2024.
- 2024 Teng Li, Amir Zakerimanesh, **Yafei Ou**, Badre Armin, and Mahdi Tavakoli. Iterative learning for gravity compensation in impedance control. *IEEE/ASME Transactions on Mechatronics (TMECH)*, pages 1–12. World Scientific Publishing Company, 2024.
- 2023 Yafei Ou, Sadra Zargarzadeh, and Mahdi Tavakoli. Robot learning incorporating human interventions in the real world for autonomous surgical endoscopic camera control. Journal of Medical Robotics Research (JMRR), volume 8, pages 2340004–1, 2023.
- 2023 **Yafei Ou** and Mahdi Tavakoli. Sim-to-real surgical robot learning and autonomous planning for internal tissue points manipulation using reinforcement learning. *IEEE Robotics and Automation Letters (RA-L)*, volume 8, pages 2502–2509. IEEE, 2023.

Conference Papers

- 2024 Yafei Ou, Sadra Zargarzadeh, Paniz Sedighi, and Mahdi Tavakoli. A realistic surgical simulator for non-rigid and contact-rich manipulation in surgeries with the da vinci research kit. In 21st International Conference on Ubiquitous Robots (UR). IEEE, 2024.
- 2023 **Yafei Ou** and Mahdi Tavakoli. Towards safe and efficient reinforcement learning for surgical robots using real-time human supervision and demonstration. In 2023 International Symposium on Medical Robotics (ISMR), pages 1–7. IEEE, 2023.

Manuscripts in Preparation

- 2024 Sadra Zargarzadeh, Maryam Mirzaei, **Yafei Ou**, and Mahdi Tavakoli. From decision to action in surgical autonomy: Multi-modal large language models for robot-assisted blood suction. *arXiv preprint arXiv:2408.07806*, 2024. submitted.
- 2024 Abed Soleymani, **Yafei Ou**, Xingyu Li, and Mahdi Tavakoli. Vaps: Encoding of human movement characteristics for dexterous robot trajectory generation. 2024. in progress.
- 2024 Yi Hu, **Yafei Ou**, August Sieben, Zahra Samadikhoshkho, Bin Zheng, and Mahdi Tavakoli. Surgical robot learning from imperfect demonstrations. 2024. submitted.

Awards & Scholarships

- 2024 Floyd Derkat Graduate Award in Artificial Intelligence and Machine Learning, University of Alberta, \$5,000.
- 2024 2025 Stephen and Olga Anhill Graduate Scholarship in Electrical and Computer Engineering, *University of Alberta*, \$12,000.
- 2023 2025 Alberta Innovates Graduate Student Scholarship (AI GSS), Alberta Innovates, \$31,000 (Actual: \$12,000), annually for 2 years.

 Awarded as a supplementary top-up amount due to holding another major award.
- 2021 2025 CSC Ph.D. Scholarship, China Scholarship Council, \$26,400, annually for 4 years.

Academic Activities and Positions

- 2023 Research Assistant, Department of ECE, University of Alberta.
- Winter 2023 **Teaching Assistant**, ECE 760: Robotics: Modelling, Planning and Control.
- Winter 2023 Scholarship Of Pedagogy and Application Of Research Knowledge Engineering (SPARK-ENG), certificate acquired.

Reviewed manuscripts for IEEE Robotics and Automation Letters (RA-L), IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), International Symposium on Medical Robotics (ISMR), among others.

Oral and poster presentations at Autonomous Systems Initiative (ASI) Symposium (University of Alberta, 2023), Biomedical Engineering Research Day (University of Alberta, 2024), among others.

Computer Skills

General-purpose programming: Python, C#, C, C++, MATLAB

Control system design and simulation: MATLAB, Simulink

Robotics: ROS, Robotics Toolbox for MATLAB/Python, OpenCV

Machine learning: PyTorch, NumPy, scikit-learn, ONNX

Video game and virtual reality: Unity, PhysX, HLSL

3D modelling: Creo, SolidWorks, Blender

Languages

English (Proficient)

Chinese (Native)